

# Megha Kalia

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◇ Research Gate

## EDUCATION

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- The University of British Columbia (UBC)** **Vancouver, Canada**  
Ph.D. Candidate, Electrical and Computer Engineering 2017 - current  
*Thesis: "Real-Time, Perceptually Coherent Augmented/Mixed Reality Applications for Surgical Interventions"*  
Advisors: Prof. S. E. Salcudean, UBC & Nassir Navab, Technical University of Munich (TUM)
- Indian Institute of Technology (IIT) Kharagpur** **Kharagpur, India**  
M.Tech., Medical Imaging and Informatics, (Grade - 8.67/10) 2014 - 2016  
*Thesis: "Methods to Improve Depth Perception in Medical Augmented Reality"*  
(Carried out at TUM with support from DAAD Scholarship)  
Advisors: Prof. Chandan Chakraborty & Nassir Navab
- Guru Gobind Singh Indraprastha University (GGSIPU)** **New Delhi, India**  
B.Tech., Biotechnology, (Grade - 71.9/100) 2010 - 2014

## RESEARCH INTERESTS

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Medical Augmented/Mixed Reality, Human Computer Interaction, Context-Aware Interface Design, Perception, Computer Vision

## AWARDS AND SCHOLARSHIPS

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- Student Travel Award, Medical Image Computing and Computer Assisted Intervention, Strasbourg, France Oct 2021
- **Best paper in Bench-to-Bedside category**, International Conference on Information Processing in Computer-Assisted Interventions (IPCAI), Munich June 2021
- Friedman Award for Scholars in Health, UBC Aug 2021 - Apr 2022
- Public Scholars Initiative Award, UBC Aug 2020 - Apr 2021
- Teaching as Research, Graduate Student Award, UBC May 2020
- **Outstanding Paper Award**, Computer Aided Intervention Workshop, Medical Image Computing and Computer Assisted Intervention, Shenzhen, China Oct 2019
- Graduate Student Initiative Award, UBC Sep 2019
- International Tuition Award, UBC 2017, 2018, 2019, 2020
- Graduate Travel Award, UBC Mar 2018
- Travel Award, Hamlyn Winter School, Imperial College London, UK Dec 2017
- DAAD (German Academic Exchange Service) Scholarship (for completion of master's thesis at TUM, Germany) Sep 2015 - Mar 2016
- BOSCH India Women Inventor of the Year (for filing two patents) 2015
- AICTE-GATE Post Graduate Scholarship, Government of India (for master's degree) 2014 - 2016

## PATENTS

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- A microscope imaging system India 4592/CHE/2015
- Meibomian gland diagnostic device India 5742/CHE/2015

## PEER-REVIEWED JOURNALS

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1. **Kalia, M.**, Avinash, A., Navab, N., & Salcudean, S. E. (2021). Preclinical Evaluation of a Marker-less, Real-time, Augmented Reality Guidance System for Robot Assisted Radical Prostatectomy. *International Journal of Computer Assisted Radiology and Surgery* (**Bench-to-Bedside Award**).
2. **Kalia, M.**, Mathur, P., Tsang, K., Black, P., Navab, N., & Salcudean, S. E. (2020). Evaluation of a marker-less, intra-operative, augmented reality guidance system for robot-assisted laparoscopic radical prostatectomy. *International Journal of Computer Assisted Radiology and Surgery*, 15, 1225-1233.
3. **Kalia, M.**, Mathur, P., Navab, N., & Salcudean, S. E. (2019). Marker-less real-time intra-operative camera and hand-eye calibration procedure for surgical augmented reality. *Healthcare technology letters*, 6(6), 255-260. (**Outstanding Paper Award**)
4. Abdelaal, A. E., Avinash, A., **Kalia, M.**, Hager, G. D., & Salcudean, S. E. (2020). A multi-camera, multi-view system for training and skill assessment for robot-assisted surgery. *International journal of computer assisted radiology and surgery*, 15, 1369-1377.

## PEER-REVIEWED CONFERENCES

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1. (Oral) **Kalia, M.**, Aleef, T., Navab, N., & Salcudean, S. E. (2021). Co-Generation and Segmentation for Generalized Surgical Instrument Segmentation on Unlabelled Data. In 2021 *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)* (pp. 403-412). Springer, Cham.
2. **Kalia, M.**, Navab, N., & Salcudean, S. E. (2019, May). A real-time interactive augmented reality depth estimation technique for surgical robotics. In 2019 *International Conference on Robotics and Automation (ICRA)* (pp. 8291-8297). IEEE.
3. **Kalia, M.**, Navab, N., Fels, S., & Salcudean, S. E. (2019, March). A Method to Introduce & Evaluate Motion Parallax with Stereo for Medical AR/MR. In 2019 *IEEE Conference on Virtual Reality and 3D User Interfaces (VR)* (pp. 1755-1759). IEEE.
4. **Kalia, M.**, zu Berge, C. S., Roodaki, H., Chakraborty, C., & Navab, N. (2016, August). Interactive depth of focus for improved depth perception. In *International Conference on Medical Imaging and Augmented Reality* (pp. 221-232). Springer, Cham.

## LEADERSHIP & SERVICE

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**Reviewer:** International Conference on Intelligent Robots and Systems (IROS), 2021. IJCARS, 2020. IJ-CARS, 2019. Medical Imaging and Augmented Reality, Augmented Environments for Computer Assisted Interventions (AE-CAI), MICCAI, 2019.

**Steering Committee Member, Biomedical Imaging and Artificial Intelligence Research Cluster**, UBC 2018 - current

Planning and organizing events to promote AI related research and outreach

**Member, Academic Policy Sub-committee**, Graduate Council Student Caucus, UBC 2018 - 2020

**Grant Writer, Kaleidoscope**, UBC mental health awareness club 2018 - 2019

**Executive Committee Member, Women in Engineering**, UBC 2017

Organized biweekly networking event to discuss gender and diversity issues at workplace

**Co-founder, Ambar, LGBTQ support group**, IIT Kharagpur 2015

Organized events to spread awareness about gender-identity related issues among students

## ACHIEVEMENTS

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- **2<sup>nd</sup> Place**, 3 Minute Thesis Competition, ECE, UBC Feb 2021

- **3<sup>rd</sup> Place**, Reboot Startup Competition, UBC Jan 2019  
*Idea: Semi-Automatic Segmentation of Multi-modal Medical Data*
- **Hult Prize Business Competition**, represented UBC in Canada Region, Toronto Mar 2018  
*Idea: Cluster farming for small farmers for maximizing profits by economies of scale.*

## RESEARCH EXPERIENCE

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**Research Assistant**, Electrical and Computer Engineering, UBC, Canada May 2017 - Current  
Project: Augmented Reality for Robot Assisted Surgery  
Advisor: Prof. S. E. Salcudean

- Coordinating with Urologists, Nurses for data recording and collection of human robotic prostate surgeries at Vancouver General Hospital (VGH)
- Building real-time, intra-operative AR visual guidance solutions for minimally invasive surgical procedures. Evaluating new methods (user studies and mathematical modelling).

**Research Assistant**, Computer Aided Medical Procedures & Augmented Reality, TUM, Germany Aug 2016 - Mar 2017

Project: Multi-Modal Medical Visualizations  
Advisors: Prof. Nassir Navab

- Software development for visualizing and evaluating AR methods using 3D data such as MRI/CT

## INDUSTRIAL EXPERIENCE

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**Summer Intern**, BOSCH Engineering and Business Solutions, Bengaluru, India Jun 2015 - Jul 2015

- Proposed a metric for quantification of the medical condition, Meibomian Gland Dysfunction, using wavelet based features and image processing techniques. The algorithm is in a clinical product.
- Filed two patents

## ADDITIONAL TRAINING

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**Medical Augmented Reality Summer School, University of Balgrist, Zurich** Aug 2019  
Two weeks of lectures and hands-on AR project on Magic Leap head mounted display

**Hamlyn Winter School on Surgical Imaging and Vision, Imperial College London, United Kingdom** Dec 2017  
One week of lectures and a hand-on project on surgical robotics

**Suicide Prevention Training (QPR-Question, Persuade, Refer), UBC** Dec 2019  
Strategies to identify and handle peers in distress

## TEACHING AND MENTORSHIP

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**Teaching Assistant**, UBC Jan 2018 - Apr 2018  
Human Computer Interaction, CPEN 441 (Undergraduate course)

**Instructional Skills Workshop**, Center for Teaching, Learning and Technology, UBC Jan 2020

**Supervisor, School of Biomedical Engineering (SBME), UBC** Summer 2020  
Abdulrahman Shinnawy (3<sup>rd</sup> year undergraduate intern)  
Student received SBME scholarship for my proposed project

**Mentor, Undergraduate Research Experience Program, UBC** Fall 2020  
Mentored 5 undergraduate students

**Poster Presentation, CTLT Winter Institute Poster** Fall 2020  
*Title: Comparing the effect of individual and group code review activities on student engagement in an online classroom*